### **ECS150 Discussion Section**

Sophie Engle ( February 11/13 2004 )

### Announcements

- Website updated!
  - Added information on compiling the Minix kernel
  - Added more hints & tips for using Minix
  - Added more common compile errors
  - Updated grades
- Will have to know how to compile the Minix kernel for next programming assignment!

# Deadlocks

- Resources
  - ◆ Tanenbaum p75 77
  - ◆ Tanenbaum p166 179

### Resources

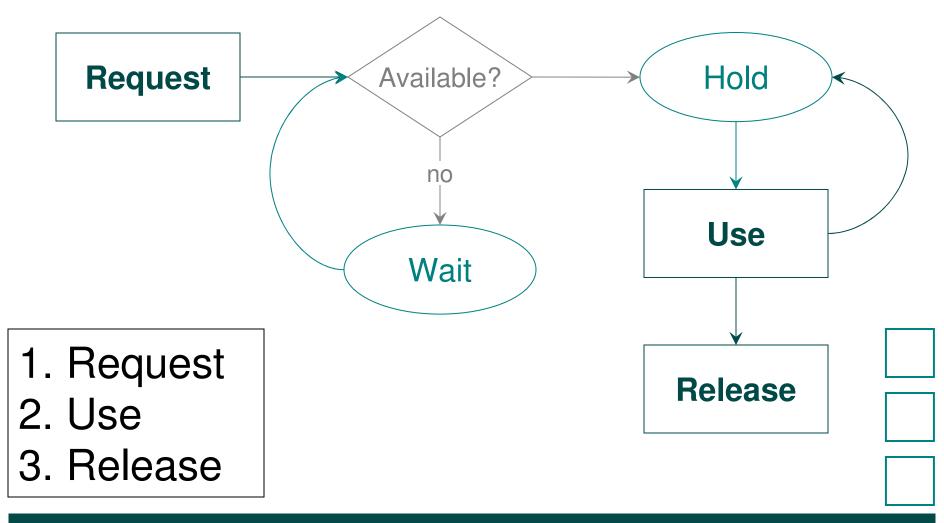
#### Resource

 Anything that can only be used by a single process at any instant

### Types

- ◆ Preemptable
  - Resource can be taken away
  - Example: Memory
- ◆ Nonpreemptable\*
  - □ Resource can NOT be taken away
  - Example: Printer

## Nonpreemptable Resources



# Deadlock

#### Definition:

 A set of processes is deadlocked if each process in the set is waiting for an event that only another process in the set can cause

### Example:

- Process 1 is holding resource A, needs B
- Process 2 is holding resource B, needs A

## Dining Philosophers

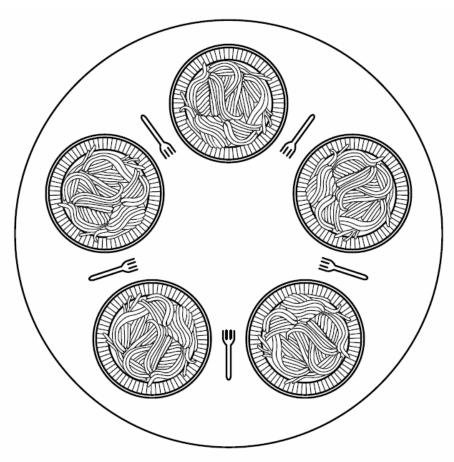


Figure 2-16. Lunch time in the Philosophy Department.

- Must have 2 forks to eat
- Everyone picks up left fork at same time and waits for right fork
- Nobody is able to eat, deadlock occurs

### Deadlock Conditions

### Necessary Conditions:

- Mutual exclusion condition
- Hold and wait condition
- No preemption condition
- Circular wait condition

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### Resource Graph

- Nodes:
  - Processes: Circle
  - Resources: Square
- Arcs:
  - ♦ Resource A → Process 1: P1 holds A



◆ Process 1 → Resource A: P1 waiting for A

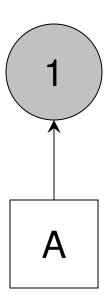


Process #	Required Resources
Process 1	A and B
Process 2	B and C
Process 3	C and A

#### **Events:**

P1 requests A

В

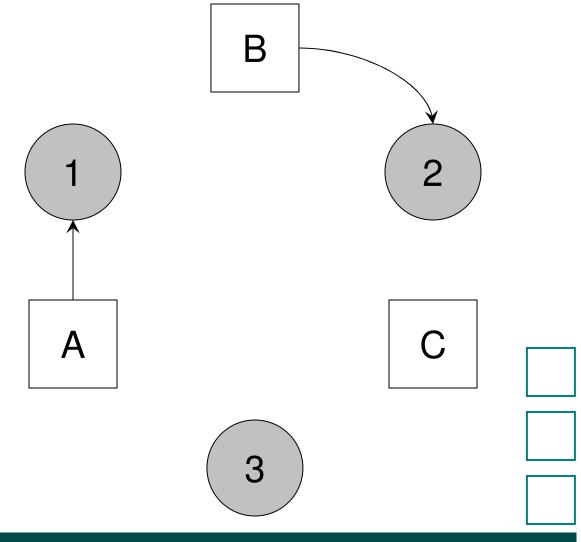


2

С

#### **Events:**

P1 requests A P2 requests B

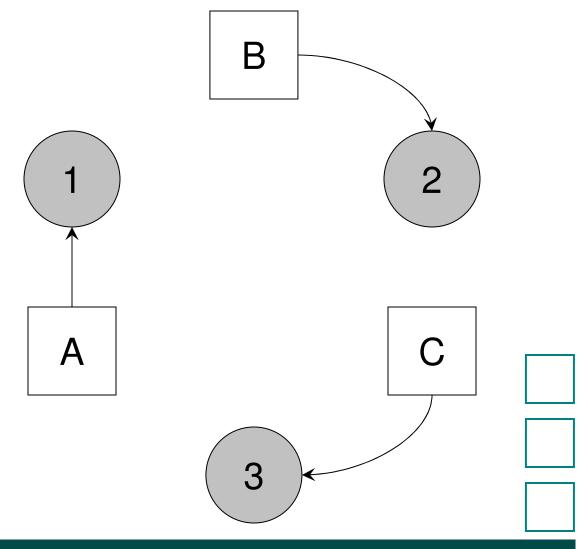


#### **Events:**

P1 requests A

P2 requests B

P3 requests C



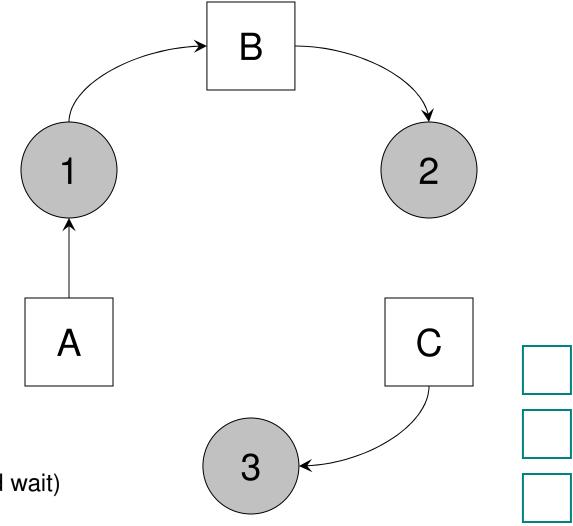
#### **Events:**

P1 requests A

P2 requests B

P3 requests C

P1 requests B



(notice example of hold and wait)

#### **Events:**

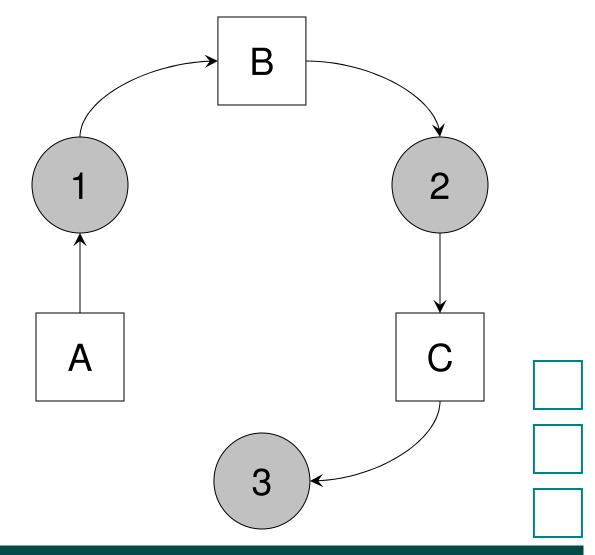
P1 requests A

P2 requests B

P3 requests C

P1 requests B

P2 requests C



#### **Events:**

P1 requests A

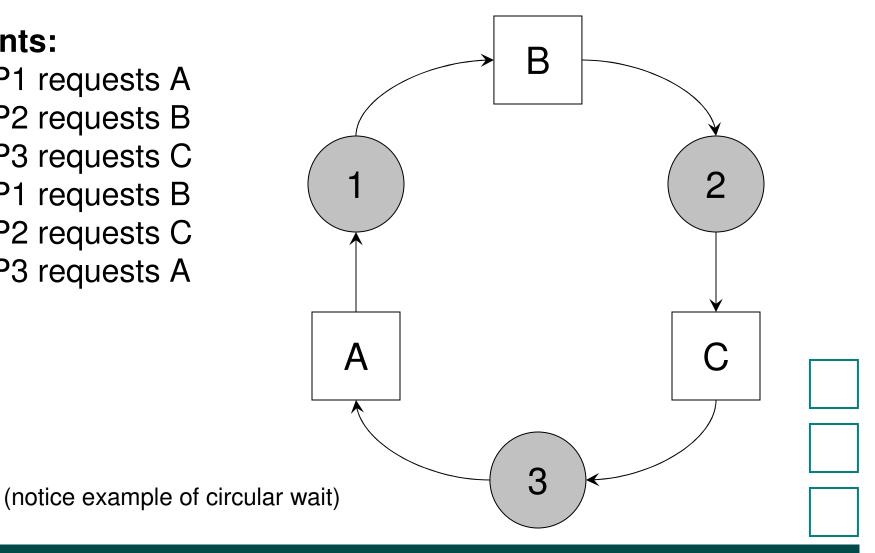
P2 requests B

P3 requests C

P1 requests B

P2 requests C

P3 requests A



# Handling Deadlocks

- Possible responses:
  - Ignore
  - Detect (and recover)
  - Avoid
  - Prevent

### Handling Deadlocks

- Possible responses:
  - Ignore
    - Are deadlocks such a bad problem?
  - Detect (and recover)
    - Watch for deadlocks, fix when happens
  - Avoid
    - Make good decisions!
  - Prevent
    - Eliminate one condition required for deadlocks

## Ignore Deadlocks

- Why ignore deadlocks?
  - How often will deadlocks occur?
  - How often will system crash anyway?
  - Is deadlock detection, prevention, or avoidance really cost effective?
- Ostrich Algorithm
  - Ignore problem of deadlocks completely

# **Detection and Recovery**

Method	Detection	Recovery
1	Keep resource graph, check for cycles	Kill a process in the cycle until cycle is broken
2	Check how long process has been continuously blocked	Kill process that has been continuously blocked for long time

# Avoidance

- Decide if resource should be granted
  - Want to keep system in a "safe" state
  - Requires certain information in advance
  - Great in theory, but often impractical

- Banker's Algorithm for Multiple Resources
  - Often discussed avoidance algorithm
  - Rarely used in practice

- Tracks current state of system
- Prevents state from becoming unsafe
  - A state is safe if there exists some sequence that allows every process to run to completion

- State tracked by:
  - 2 Process by Resource Matrices
    - Resources assigned
    - Resources still needed
  - 3 Resource Vectors
    - □ (E)xisting resources
    - □ (P)ossessed resources
    - □ (A)vailable resources

#### To check if initial state safe:

- Find process whose needs are less than the available resources
  - If none exist, then state not safe (deadlock possible)
- 2. Assume process completes, and add its resources as available
- Repeat steps 1 and 2 until all processes are terminated
  - If possible, then initial state safe

												sse	ole
	assigned						still	nee	existing	possesse	available		
	Α	В	С	D	Е	Α	В	С	D	Ε	exi	od	ava
tape drives	3	0	1	1	0	1	0	3	0	2	6	5	1
plotters	0	1	1	1	0	1	1	1	0	1	3	3	0
printers	1	0	1	0	0	0	1	0	1	1	4	2	2
cd-roms	1	0	0	1	0	0	2	0	0	0	2	2	0

Process = D											<u>ත</u>	pessessod	ole .		
		as	sign	ed			still	nee		existing	sses	available			
	Α	В	С	D	Е	Α	В	С	D	Е	exi	exis			
tape drives	3	0	1	1	0	1	0	3	0	2	6	5	1		
plotters	0	1	1	1	0	1	1	1	0	1	3	3	0		
printers	1	0	1	0	0	0	1	0	1	1	4	2	2		
cd-roms	1	0	0	1	0	0	2	0	0	0	2	2	0		

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	Α	В	С	B	Е	Α	В	С	D	Ε	exi	od	ava
tape drives	3	0	1		0	1	0	3	0	2	6	4	2
plotters	0	1	1		0	1	1	1	0	1	3	2	1
printers	1	0	1	8	0	0	1	0		1	4	2	2
cd-roms	1	0	0		0	0	2	0	0	0	2	1	1

Eventually, all will be able to run. Initial state = safe

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		as	sign	ed			still	nee	existing	posses	ailabl		
	A	В	С	D	Е	A	В	С	D	Ε	exi	öd	ava
tape drives	3	0	1	***	0	**	0	3	0	2	6	2	4
plotters	Ø	1	1	**	0	X	1	1	Ø	1	3	2	1
printers		0	1	Ø	0	Ø	1	0	**	1	4	2	2
cd-roms		0	0	*	0	Ø	2	0	Ø	0	2	0	3

### **Deadlock Prevention**

- Impose restrictions that make deadlocks structurally impossible
  - Prevent at least one of four conditions required for deadlock to occur
- How prevent deadlock?
  - Prevent mutual exclusion?
  - Prevent hold and wait condition?
  - Prevent no preemption condition?
  - Prevent circular wait condition?

### Deadlock Conditions

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